

# The Intellectual Ascent to Agda

David Sankel  
Stellar Science

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# Quiz

Are the following two C++ programs the same?



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```
#include <iostream>

int main( int argc, char** argv )
{
    std::cout << "Hello World\n";
}
```

```
#include <iostream>

int main( int argc, char** argv )
{
    std::      cout << "Hello World\n";
}
```

# Quiz

Are the following two programs the same?

```
#include <iostream>

int main( int argc, char** argv )
{
    std::cout << "Hello World\n";
}
```

```
print("Hello World")
```

# Quiz

Are the following two programs the same?

```
int f( int c )
{
    if( false )
        return 45;
    else
        return c + 5;
}
```

```
int f( int c )
{
    int j = 5;
    j += c;
    return j;
}
```

# Essence of Programs

Ideally we would like:

- Strong equivalence properties
- Something written down
- A set of rules we can apply to any program

*Any ideas of what would be a good intermediate language?*

# How about math?

$$3 + 2 = 5$$

$$5 = 3 + 2$$

# Denotational Semantics

Developed by Dana Scott and Christopher Strachey  
in late 1960s

Write a mathematical function to convert syntax to  
meaning (in math).

$\mu[e_1 + e_2] = \mu[e_1] + \mu[e_2]$  where  $e_i$  is an expression  
 $\mu[i] = i$  where  $i$  is an integer



# What is the meaning of this?

```
int f( int c )  
{  
    if( false )  
        return 45;  
    else  
        return c + 5;  
}
```

# Function Meaning

We could represent a  
function as a set of pairs  
As in:

$\{ \dots, (-1, 44), (0, 45), (1, 46), \dots \}$

```
int f( int c )  
{  
  if( false )  
    return 45;  
  else  
    return c + 5;  
}
```

Or as a lambda equation:  $\lambda c. c + 5$

Or something else:  $f(c) = c + 5$

# Function Meaning

What about this?

```
int f( int c )  
{  
  for(;;) ;  
  return 45;  
}
```

$\dots, (-1, \perp), (0, \perp), (1, \perp), \dots$

$\perp$  is “bottom”

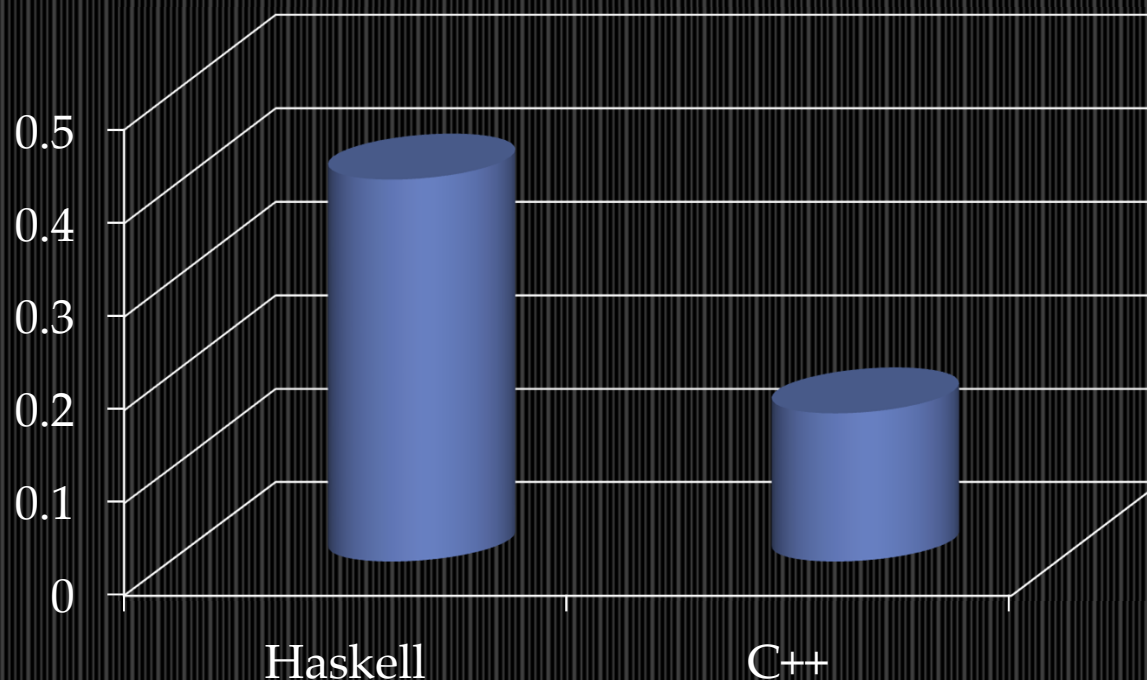
# The Next 700 Programming Languages

P. J. Landin wrote in 1966 about his programming language ISWIM (If you See What I Mean)

$f(b+2c) + f(2b-c)$   
**where**  $f(x) = x(x+a)$

# Why not drop the C++ nonsense and go Haskell?

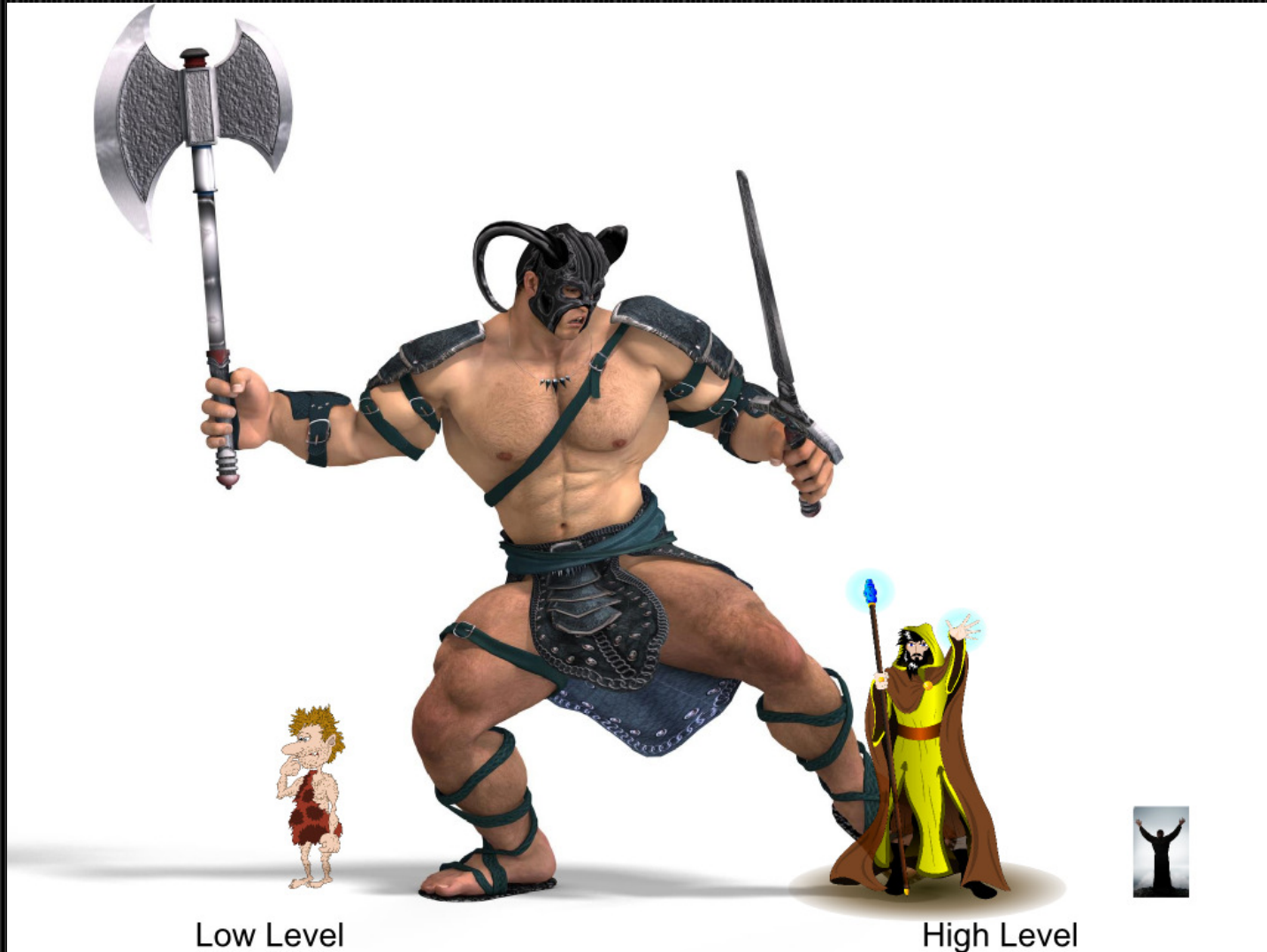
Quicksort 160,000 ints



Haskell variant with optimizations: 0.41s

C++ variant without optimizations: 0.16s

# Languages and Machines



# Denotational Design

- Conal Elliott, various applications of denotational design throughout career.
- See ‘Denotational design with type class morphisms’.
- Main idea:
  - Design semantics in Haskell without regard to performance.
  - Derive a speedy implementation in Haskell using the semantics.



# Agda





# Types in Agda

$a : \text{int}$

$a = 5$

Agda as semantic domain for C++ expressions:

$\mu[3 + 2] = 5$

$\mu[3 + 2] : \text{int}$

$\mu[e_1 + e_2] : \text{int}$  where  $e_i$  is an int expression



# Functions in Agda

“ $a \rightarrow b$ ” is the type of functions with input ‘a’ and output ‘b’.

Consider:

```
int f( char c ) { return 4; }
```

In Agda we would write something like ,

```
f : char → int
```

```
f c = 4
```

Calling functions is done without parentheses. So,  $f('a')$  would become  $f\ 'a'$  instead.

Multiple parameter function types are written like:

```
char → int → char
```

# Pairs in Agda

$\mathbf{a} \times \mathbf{b}$  is a pair type where the first element has type  $\mathbf{a}$  and the second element has type  $\mathbf{b}$ . It is also called a product type.

A value of type  $\mathbf{a} \times \mathbf{b}$  is written as  $(x,y)$  where  $x$  has type  $\mathbf{a}$  and  $y$  has type  $\mathbf{b}$ .

So with denotational semantics, we can say  
 $\mu \llbracket \text{std}::\text{pair}\langle \mathbf{a}, \mathbf{b} \rangle \rrbracket_{\mathbf{T}} = \mu \llbracket \mathbf{a} \rrbracket \times \mu \llbracket \mathbf{b} \rrbracket$

Note: We're using T and E subscripts to differentiate between type and expression contexts where there is ambiguity.

# Magic: Types of Types

Types have a “type” too (a universe actually).

$\text{Int} : \text{Set}$

Here’s a function type. It’s “type” is also Set.

$\text{Int} \rightarrow \text{Char} : \text{Set}$

Set has a type too:  $\text{Set} : \text{Set1}$

*Any ideas why Set’s type isn’t Set?*

# Magic: Type-Value Mixing

Types and values can be mixed.

```
intToType : Int -> Set
```

```
intToType 0 = Char
```

```
...      _ = Int
```

How would you write this function in C++?



# Magic: Type-Value Mixing

```
intToType : Int -> Set
```

```
intToType 0 = Char
```

```
...      _ = Int
```

```
template< int i > struct intToType { typedef int type; }
```

```
template<> struct intToType<0>{ typedef char type; }
```

```
// Call it like this (z = intToType 0)
```

```
typedef intToType<0>::type z
```

# Magic: Dependent Types

We can figure out the saturated vector type's meaning's type. It is just another type. (We're still in the type context)

$$\mu \llbracket \text{std::vector<char>} \rrbracket_{\top} : \text{Set}$$

So what is 'std::vector' by itself (lets ignore the allocator)?

$$\mu \llbracket \text{std::vector} \rrbracket_{\top} : ?$$
$$\mu \llbracket \text{std::vector} \rrbracket_{\top} : \text{Set} \rightarrow \text{Set}$$

# Magic: Dependent Types

$\mu \llbracket \text{std}::\text{pair} \rrbracket_{\top} : \text{Set} \rightarrow \text{Set} \rightarrow \text{Set}$   
 $\mu \llbracket \text{std}::\text{pair} \rrbracket_{\top} = \lambda a\ b. a \times b$

What about `std::pair` in an expression context? Here we have two type parameters and two value parameters.

$\mu \llbracket \text{std}::\text{pair} \rrbracket_E = \lambda t_0\ t_1\ v_0\ v_1. (v_0, v_1)$

What about the type?

$\mu \llbracket \text{std}::\text{pair} \rrbracket_E : ?$

$\mu \llbracket \text{std}::\text{pair} \rrbracket_E : \text{Set} \rightarrow \text{Set} \rightarrow ? \rightarrow ? \rightarrow ?$

$\mu \llbracket \text{std}::\text{pair} \rrbracket_E : (t_0 : \text{Set}) \rightarrow (t_1 : \text{Set}) \rightarrow t_0 \rightarrow t_1 \rightarrow t_0 \times t_1$



# Magic: Dependent Types

Dependent function type

General form is  $(x : t) \rightarrow e(x)$ .

- $x$  is an identifier.
- $t$  is a type.
- $e(x)$  is an expression that uses ' $x$ ' in it.

# Dependent Types 2

Another kind of dependent type.

```
type_and_value : (a : Set) × a  
type_and_value = (Int,3)
```

Here we have a pair of a type and an element of that type.

```
make_type_and_value : (a : Set) → a → (b : Set) × b  
make_type_and_value t v = ( t, v )
```

# Implicit types

Recall the type of `std::pair`'s meaning:

$$\mu[\text{std::pair}]_E : (t_0 : \text{Set}) \rightarrow (t_1 : \text{Set}) \rightarrow t_0 \rightarrow t_1 \rightarrow t_0 \times t_1$$

`std::make_pair` also has all these arguments, but the type arguments are implied. Use `{}` for implied types

$$\mu[\text{std::make\_pair}] : \{t_0 : \text{Set}\} \rightarrow \{t_1 : \text{Set}\} \rightarrow t_0 \rightarrow t_1 \rightarrow t_0 \times t_1$$

Now `std::make_pair`'s meaning can be called with only two arguments.

# Denotational Design

What is a movie?



# What is a movie?

- $\mu[\text{Movie}] : \text{Set} \rightarrow \text{Set}$
- $\mu[\text{Movie}] = \lambda a \rightarrow (\mathbb{R} \rightarrow a)$

Operations:

$\mu[\text{always}] : \{ A : \text{Set} \} \rightarrow A \rightarrow \mu[\text{Movie}] A$

$\mu[\text{always}] a = \lambda t. a$

$\mu[\text{snapshot}] : \{ A : \text{Set} \} \rightarrow \mu[\text{Movie}] A \rightarrow \mathbb{R} \rightarrow A$

$\mu[\text{snapshot}] m t = m t$

# What is a movie?

$\mu[\text{leftTrim}] : \{ A : \text{Set} \} \rightarrow \mathbb{R} \rightarrow \mu[\text{Movie}] A \rightarrow \mu[\text{Movie}] (\mu[\text{boost}::\text{optional}]_T A)$

$\mu[\text{leftTrim}] \text{trimTime } m = \lambda t.$

if  $(t < \text{trimTime})$

then  $\mu[\text{boost}::\text{none}]$

else  $\mu[\text{boost}::\text{make\_optional}] (m \ t)$

$\mu[\text{app}] : \{ A : \text{Set} \} \rightarrow \{ B : \text{Set} \} \rightarrow \mu[\text{Movie}] (A \rightarrow B) \rightarrow \mu[\text{Movie}] A \rightarrow \mu[\text{Movie}] B$

# Semantics to C++

```
template< typename T >
Movie<T> cutAndPlace(
    Movie<T> mb, Time bStart, Time bDuration,
    Movie<T> ma, Time aPlacement )
{
    const auto leftTrimmed = trimLeft( mb, bStart )
    const auto rightTrimmed = trimRight( leftTrimmed, bStart + bDuration );
    // join converts Movie<optional<optional<T>>> to Movie< optional<T> >
    const auto joined = join( rightTrimmed );
    const auto shifted = shift( joined, bStart - aPlacement );

    //  $\mu[\text{overlay}] : \{a : \text{Set}\} \rightarrow \text{Movie } a \rightarrow \text{Movie (optional } a) \rightarrow \text{Movie } a$ 
    return overlay( ma, shifted );
}
```

# Denotational Design

1. Discover the essence of the problem you'd like to solve in pure mathematics augmented with Agda notation.
2. Implement the solution efficiently in C++ while *retaining the interface* your semantics imply.



# What is the meaning of this?

```
class Measurement
{
public:
    void setId( const int id )
    int id() const;
    std::string name;
    virtual void storeToDisk(...);
    virtual void loadFromDisk(...);
    // when returns false, this isn't valid for the geography
    virtual bool validate( Geography & )=0;
    virtual ~Measurement();
protected:
    virtual int calculateld() = 0;
}
```

# What is the meaning of this?

elsewhere...

```
class GrassMeasurement : public Measurement
{
public:
    virtual void storeToDisk(...);
    virtual void loadFromDisk(...);
    virtual bool validate( Geography &);
    Color greenThreshold;
protected:
    virtual int calculateId();
}

GrassMeasurementResult makeGrassMeasurement(
    GrassMeasurement & m,
    Geography & g );
```

# Meaning of Measurement

What is a measurement?

$\mu \llbracket \text{Measurement} \rrbracket_T = ( a : \text{Set}, \text{Geography} \rightarrow a )$

What is a grass measurement?

$\mu \llbracket \text{GrassMeasurement} \rrbracket_E : \text{Color} \rightarrow \text{Measurement}$

$\mu \llbracket \text{GrassMeasurement} \rrbracket_E =$

$\lambda \text{ greenThreshold} \rightarrow ( \text{GrassMeasurementResult}$   
 $, (\lambda \text{ geography} \rightarrow \dots) )$

# Implementation of Measurement

$\mu[\text{Measurement}]_T = (a : \text{Set}, \text{Geography} \rightarrow a)$

```
template< typename T >
struct Measurement
{
    typedef T measurement_result;
    virtual T run_measurement( const Geography & ) const=0;
};
```

# Implementation of Measurement

$\mu[\text{Measurement}]_T = (a : \text{Set}, \text{Geography} \rightarrow a)$

```
template< typename T >
struct Measurement
{
    typedef T result_type;
    virtual T operator()( const Geography & ) const=0;
};
```

# Id thing

$\mu[\text{Measurement}]_T = (a : \text{Set}, \text{Geography} \rightarrow a)$

What about that id thing?

```
template< typename T, typename Derived >
struct Measurement
{
    typedef T result_type;
    virtual T operator()( const Geography & ) const=0;
    virtual bool operator==( const Derived & ) const=0;
};
```

# Validation Thing

What about that validation thing?

$\mu[\text{Measurement}]_T = (a : \text{Set}, \text{Geography} \rightarrow a)$

$\mu[\text{Measurement}]_T = (a : \text{Set}, \text{Geography} \rightarrow \text{Optional } a)$

```
template< typename T, typename Derived >
struct Measurement
{
    typedef boost::optional<T> result_type;
    virtual result_type operator()( const Geography & ) const=0;
    virtual bool operator==( const Derived & ) const=0;
};
```

# Validation Speed

$\mu \llbracket \text{Measurement } \rrbracket_T = ( a : \text{Set}, \text{Geography} \rightarrow \text{Optional } a )$

```
template< typename T, typename Derived >
struct Measurement
{
    typedef boost::optional<T> result_type;
    virtual result_type operator()( const Geography & ) const=0;
    virtual bool operator==( const Derived & ) const=0;
    virtual bool returns_value( const Geography & g ) const
    {
        return bool( this->operator()( g ) );
    }
};

 $\mu \llbracket m.\text{returns\_value}( g ) \rrbracket = \text{boolFromOptional } ((\text{second } \mu \llbracket m \rrbracket) \mu \llbracket g \rrbracket)$ 
```



# Grass Measurement

$\mu \llbracket \text{GrassMeasurement} \rrbracket_E : \text{Color} \rightarrow \text{Measurement}$

$\mu \llbracket \text{GrassMeasurement} \rrbracket_E = \lambda \text{greenThreshold} \rightarrow ( \text{GrassMeasurementResult} , (\lambda \text{geography} \rightarrow \dots) )$

```
struct GrassMeasurement
```

```
    : Measurement< GrassMeasurementResult, GrassMeasurement>
```

```
{
```

```
    optional<GrassMeasurementResult> operator()( const Geography & ) const{...}
```

```
    bool operator==( const GrassMeasurement & gm) const
```

```
        { return greenThreshold == gm.greenThreshold; }
```

```
    bool returns_value( const Geography & g ) const { ... }
```

```
    GrassMeasurement( Color greenThreshold ) {...};
```

```
    Color greenThreshold;
```

```
};
```

# Serialization

$\mu \llbracket \text{Measurement} \rrbracket_{\tau} = ( a : \text{Set}, \text{Geography} \rightarrow a )$

1. Use Boost.Serialization for all the subclasses.
2. Make an AnyMeasurement type.

```
typedef boost::mpl::set  
  < GrassMeasurement  
    , AnotherMeasurement  
    , ...  
  > MeasurementTypes;
```

```
typedef boost::make_variant_over<MeasurementTypes>  
  AnyMeasurement;
```

# AnyMeasurement

$\mu \llbracket \text{Measurement} \rrbracket_{\tau} = ( a : \text{Set}, \text{Geography} \rightarrow a )$

AnyMeasurement looks a lot like a Measurement!

```
typedef boost::mpl::map
  < boost::result_of
    < _1 ( Geography ) >
    , MeasurementTypes
    > MeasurementResultTypes;
typedef boost::make_variant_over
  < MeasurementResultTypes > AnyMeasurementResult;
```

# AnyMeasurementType

```
struct AnyMeasurement
: Measurement< AnyMeasurementResult, AnyMeasurement >
{
    typedef boost::make_variant_over< MeasurementTypes > Impl;
    Impl impl;

    bool operator==( AnyMeasurement & m ) const { return m.impl
== impl; }
    optional< AnyMeasurementResult > operator()( const
Geography & g )
    {
        boost::apply_visitor(...);
    }
    //...
};
```

# Other operations native to semantics

$\mu \llbracket \text{Measurement} \rrbracket_{\tau} = ( a : \text{Set}, \text{Geography} \rightarrow a )$

$\mu \llbracket \text{joinMeasurements}( m1, m2 ) \rrbracket$   
= ( first  $\mu \llbracket m1 \rrbracket \times$  first  $\mu \llbracket m2 \rrbracket$   
  ,  $\lambda g. ( ( \text{second } \mu \llbracket m1 \rrbracket ) g$   
          , ( second  $\mu \llbracket m2 \rrbracket ) g$   
          )  
  )  
)

$\mu \llbracket \text{map}( f, m ) \rrbracket = ( \text{result\_of } \mu \llbracket f \rrbracket , \lambda g. f ( ( \text{second } \mu \llbracket m \rrbracket ) g ) )$

$\text{result\_of} : \{ a : \text{Set} \} \{ b : \text{Set} \} \rightarrow ( a \rightarrow b ) \rightarrow \text{Set}$   
 $\text{result\_of } \{ a \} \{ b \} \_ = a$

# Beautiful/Powerful API

```
auto grassAndRocksMeasurement =  
    map  
    ( []( GrassMeasurementResult & gmr, RocksMeasurementResult & rmr )  
      {  
        return gmr.aboveThreshold() && rmr.over100RocksFound();  
      }  
    , joinMeasurements  
      ( GrassMeasurement( Color( 0, 1, 0 ) )  
        , RocksMeasurement()  
      )  
    );  
  
Geography geo = ...  
if( grassAndRocksMeasurement.return_value( geo ) )  
    std::cout << "Cannot determine if there are grass and rocks\n";  
else  
    std::cout << "Finding of grass and rocks: " << grassAndRocksMeasurement( geo ) <<  
    '\n';
```

# The Intellectual Ascent to Agda

1. Discover the essence
  2. Derive the implementation
- Beautiful API's
  - Screaming Speed

